

# ELEN E3401: Electromagnetics

Spring 2025

Prof. Keren Bergman

Lecture #15

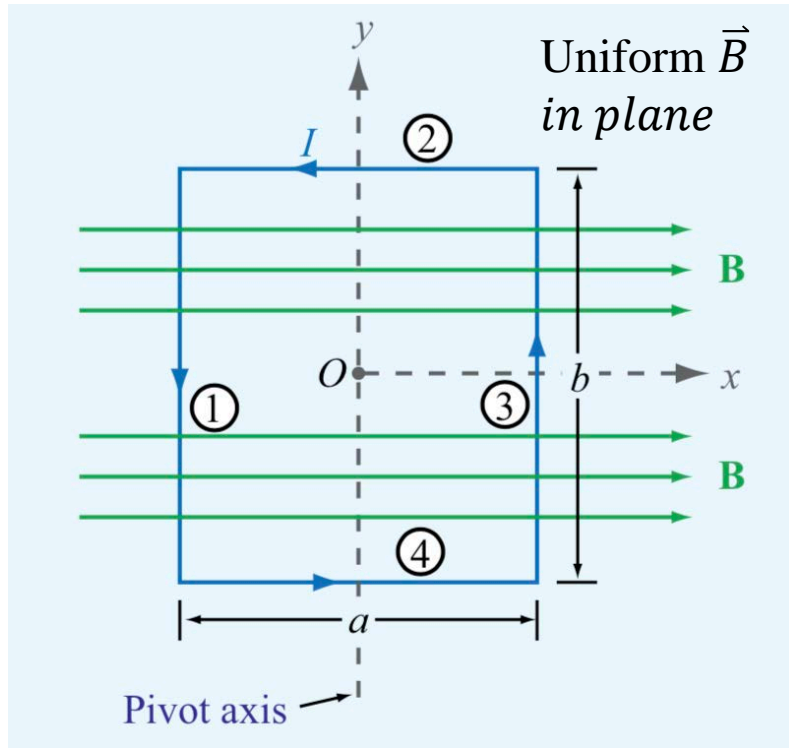


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# Magnetic torque on current carrying loop

Consider loop in x-y plane,  $\vec{B} = \hat{x}B_0$



Force on each of the 4 wire segments:

$$\vec{F}_1 = I(-\hat{y}b) \times \hat{x}(B_0) = \hat{z}IbB_0$$

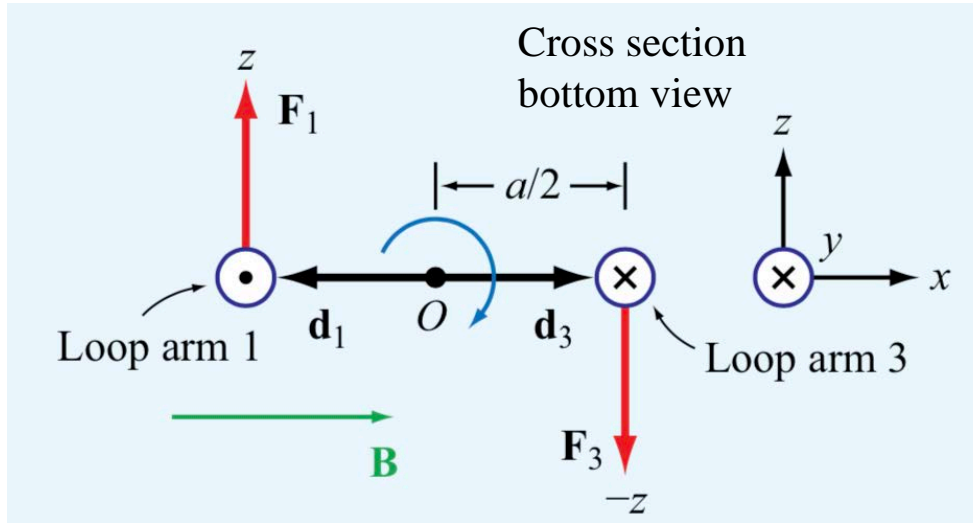
$$\vec{F}_3 = I(\hat{y}b) \times \hat{x}(B_0) = -\hat{z}IbB_0$$

$$\vec{F}_2 = 0 \quad \vec{F}_4 = 0$$

→  $\vec{B}$  is parallel to  $I$

# Magnetic torque on current carrying loop

Consider loop in x-y plane,  $\vec{B} = \hat{x}B_0$



Total force is 0 but -  
 $\vec{F}_1$  and  $\vec{F}_3$  produce a torque  
 loop will rotate clockwise

Moment arm  $\rightarrow a/2$      $\vec{d}_1 = -\hat{x}\frac{a}{2}$      $\vec{d}_3 = +\hat{x}\frac{a}{2}$

$$\vec{T} = \vec{d}_1 \times \vec{F}_1 + \vec{d}_3 \times \vec{F}_3$$

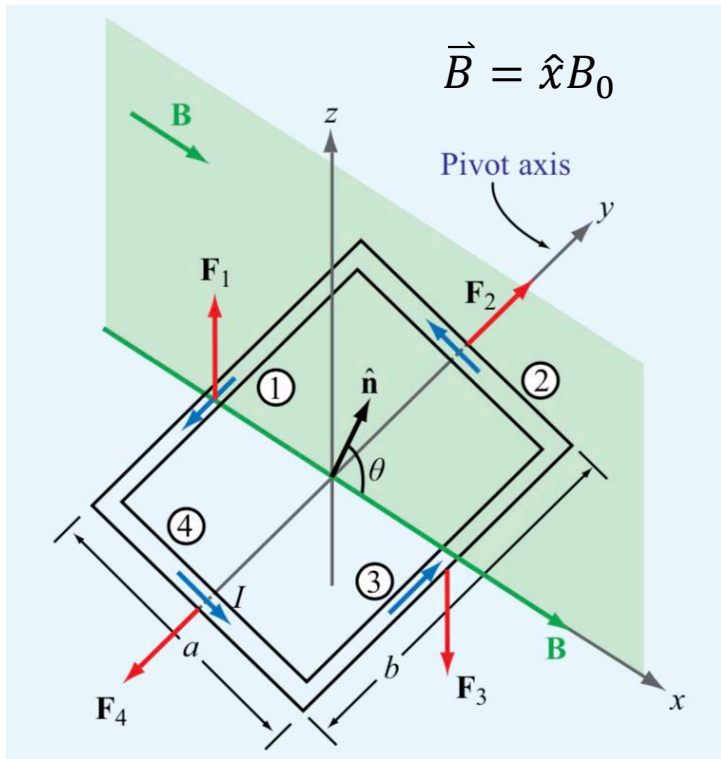
$$\vec{T} = \left(-\hat{x}\frac{a}{2}\right) \times (\hat{z}IbB_0) + \left(\hat{x}\frac{a}{2}\right) \times (-\hat{z}IbB_0)$$

$$\vec{T} = \hat{y}IabB_0 = \hat{y}IAB_0 \quad A = ab \rightarrow \text{loop cross sectional area}$$

# Rectangular Loop

Now the loop rotates

but after  $\frac{1}{4}$  turn: Torque  $\rightarrow 0$



$\vec{F}_2$  and  $\vec{F}_4$  still along rotation axis

Only  $\vec{F}_1$  and  $\vec{F}_3$  contribute to torque

$\hat{n}$  = surface normal to loop

RHR: fingers around direction of current and thumb along direction of  $\hat{n}$

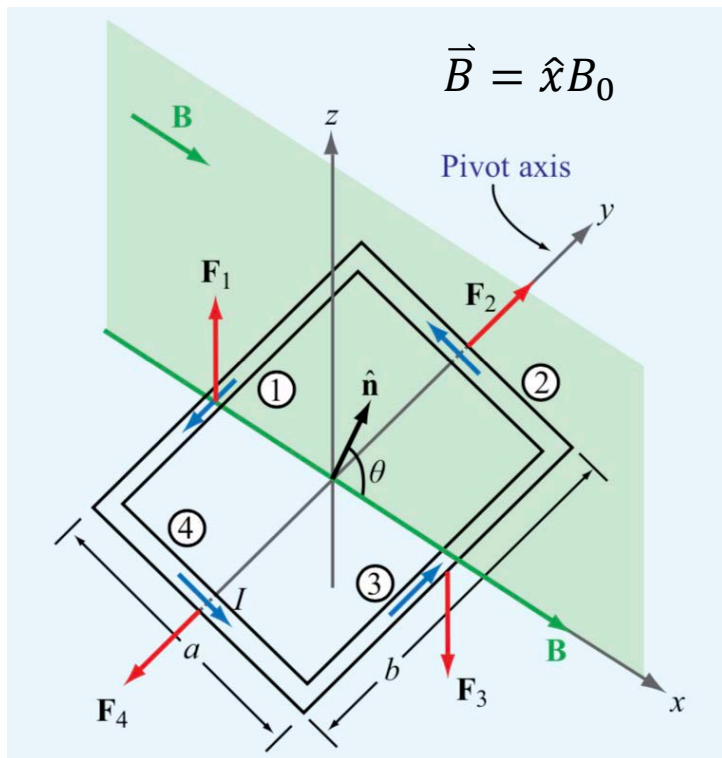
$$\text{moment arm} = \left(\frac{a}{2}\right)\sin\theta$$

Net torque:  $T = IAB_0\sin\theta$        $\vec{B} = \hat{x}B_0$

$\theta = 90^\circ \rightarrow \vec{B}$  is parallel to loop; Torque max

$\theta = 0^\circ \rightarrow \vec{B}$  is perpendicular to loop; Torque = 0

# Rectangular Loop



$$\text{moment arm} = \left(\frac{a}{2}\right)\sin\theta \quad \vec{B} = \hat{x}B_0$$

$$\text{Net torque: } T = IAB_0\sin\theta$$

$\theta = 90^\circ \rightarrow \vec{B}$  is parallel to loop; Torque max

$\theta = 0^\circ \rightarrow \vec{B}$  is perpendicular to loop; Torque = 0

If we add  $N$  turns of wire:

$$T = \underbrace{NIAB_0}_{\text{“magnetic moment”}} \sin\theta$$

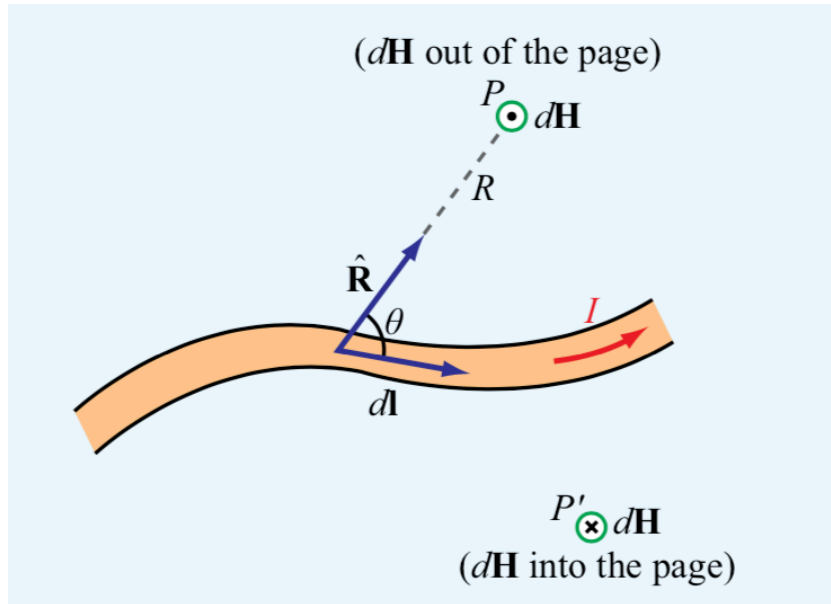
“magnetic moment” magnitude

$$\vec{m} = \hat{n}NIA = \hat{n}m$$

$$\vec{T} = \vec{m} \times \vec{B} \quad [\text{N} \cdot \text{m}] \quad \text{And applies to any shape, any direction } \vec{B}$$

# Biot-Savart Law

Jean Biot + Felix Savart → relate magnetic field  $\vec{H}$  to its generating current,  $\vec{I}$



Magnetic field,  $d\vec{H}$  generated by current element  $I d\vec{l}$

$d\vec{l}$ : along direction of current flow

$\hat{R}$ : points from current element to observation point

$d\vec{H}$  varies with:  $\frac{1}{R^2}$  (similar to  $\vec{E}$ )

Note:

$\vec{E}$  points along  $\vec{R}$

$\vec{H}$  is orthogonal to  $d\vec{l}$  and  $\hat{R}$

$$d\vec{H} = \frac{I}{4\pi} \frac{d\vec{l} \times \hat{R}}{R^2} \quad [\text{A/m}] \quad (\vec{R} = \hat{R}R)$$

$d\vec{H}$  generated by steady current,  $I$  flowing through  $d\vec{l}$

# Magnetic field due to current and current distributions

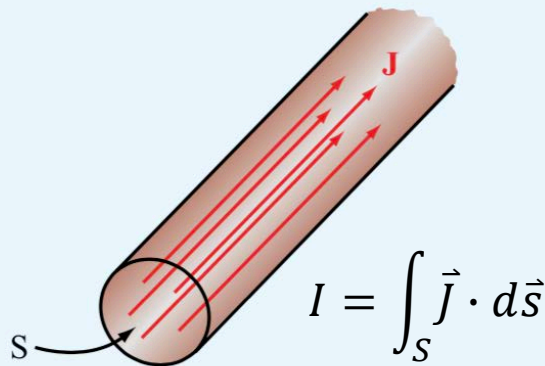
To determine total magnetic field,  $\vec{H} \rightarrow$  sum up contributions of current elements:

$$\vec{H} = \frac{I}{4\pi} \int_l \frac{d\vec{l} \times \hat{R}}{R^2}$$

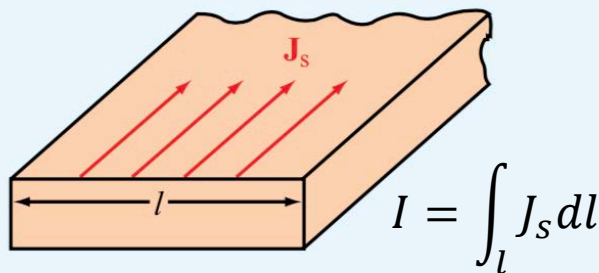
$$Id\vec{l} \rightarrow \vec{J}_s ds \rightarrow \vec{J} d\mathcal{V} \quad (\text{volume})$$

$$\vec{H} = \frac{1}{4\pi} \int_{\mathcal{V}} \frac{\vec{J} \times \hat{R}}{R^2} d\mathcal{V} \quad \text{Volume current}$$

$$\vec{H} = \frac{1}{4\pi} \int_S \frac{\vec{J}_s \times \hat{R}}{R^2} ds \quad \text{Surface current}$$

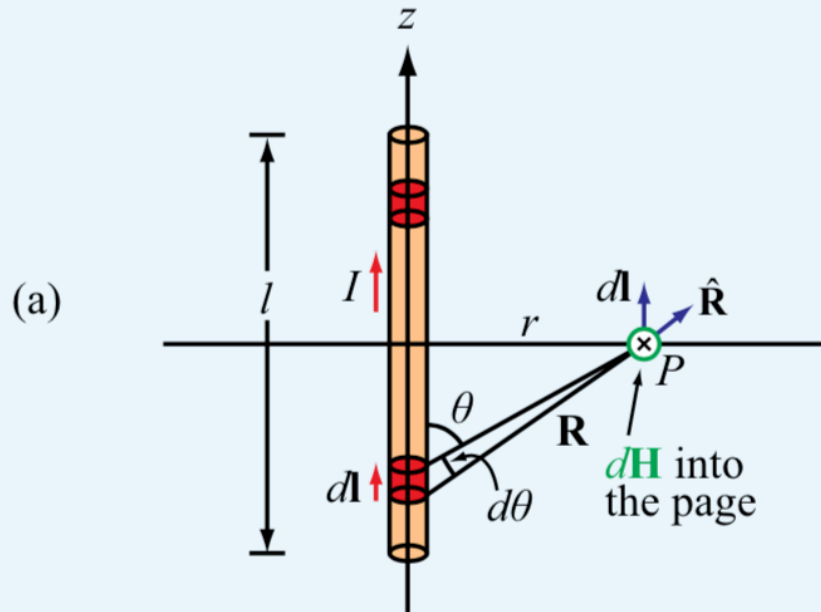


(a) Volume current density  $\mathbf{J}$  in A/m<sup>2</sup>



(b) Surface current density  $\mathbf{J}_s$  in A/m

# Magnetic field of linear conductor



Conductor length,  $l$  carrying current  $I$  along  $+\hat{z}$

Determine  $\vec{B}$  at point,  $P$ , located distance  $r$  in the  $x$ - $y$  plane

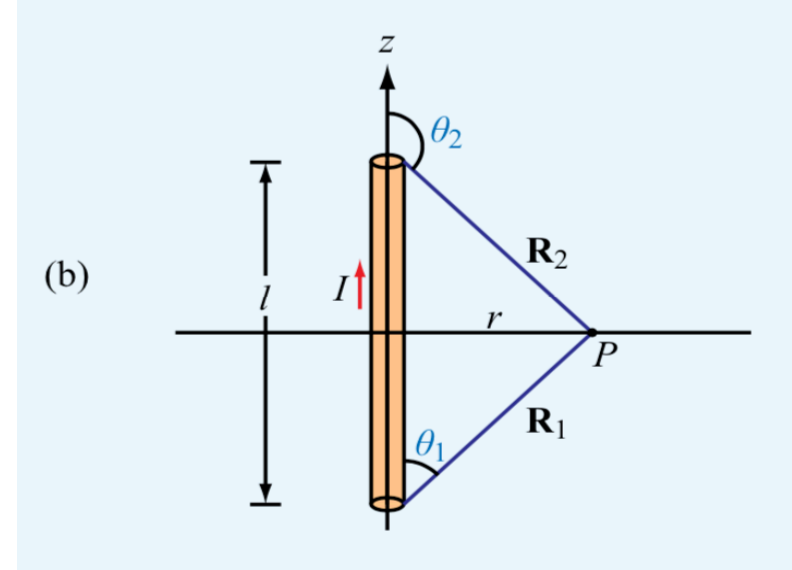
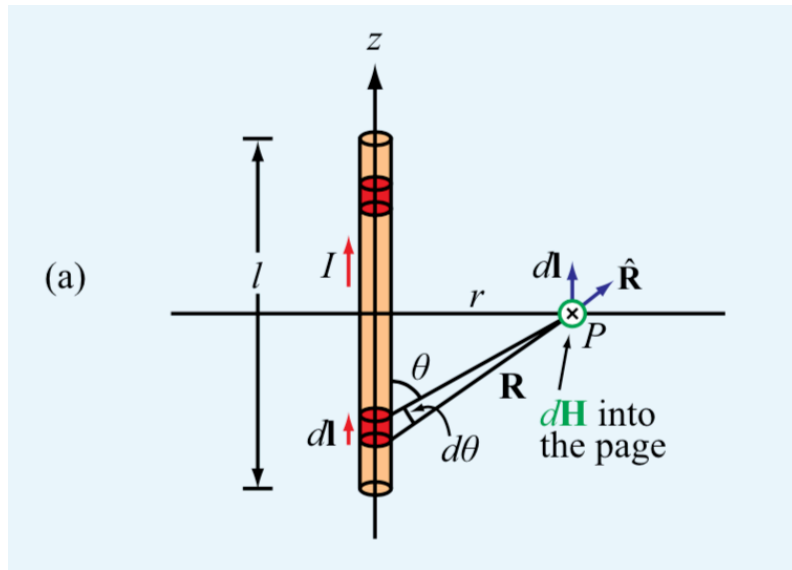
$$\vec{H} = \frac{I}{4\pi} \int_l \frac{d\vec{l} \times \hat{R}}{R^2}$$

Differential length vector:  $d\vec{l} = \hat{z}dz$

$$d\vec{l} \times \hat{R} = dz(\hat{z} \times \hat{R}) = \underbrace{\hat{\phi} \sin\theta}_{\theta = \text{angle between } d\vec{l} \text{ and } \hat{R}} dz$$

$\theta = \text{angle between } d\vec{l} \text{ and } \hat{R}$

# Magnetic field of linear conductor



Limiting angles  $\theta_1, \theta_2$  each measured between vector  $I d\vec{l}$  and vector connecting end of conductor associated with that angle to point  $P$

$$\vec{H} = \frac{I}{4\pi} \int_{z=-l/2}^{z=l/2} \frac{d\vec{l} \times \hat{R}}{R^2} = \hat{\phi} \frac{I}{4\pi} \int_{-l/2}^{l/2} \frac{\sin\theta}{R^2} dz$$

Both  $R$  and  $\theta$  depend on  $z$

# Magnetic field of linear conductor

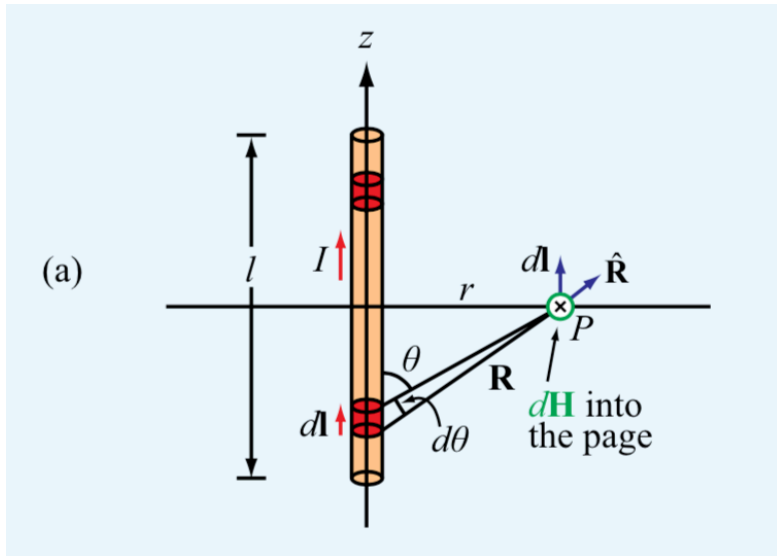
$$\vec{H} = \hat{\phi} \frac{I}{4\pi} \int_{-l/2}^{l/2} \frac{\sin\theta}{R^2} dz \quad \text{both } R \text{ and } \theta \text{ depend on } z$$

$$\csc\theta = \frac{1}{\sin\theta}$$

We change integration variable from  $z \rightarrow$  to  $\rightarrow \theta$

$$R = r \csc\theta \quad z = -r \cot\theta \quad dz = r \csc^2\theta d\theta \quad \sin\theta = \frac{r}{R}$$

$$\tan\theta = \frac{-r}{z}$$



$$\vec{H} = \hat{\phi} \frac{I}{4\pi} \int_{\theta_1}^{\theta_2} \frac{\sin\theta r \csc^2\theta d\theta}{r^2 \csc^2\theta}$$

$$\begin{aligned} \vec{H} &= \hat{\phi} \frac{I}{4\pi r} \int_{\theta_1}^{\theta_2} \sin\theta d\theta \\ &= \hat{\phi} \frac{I}{4\pi r} (\cos\theta_1 - \cos\theta_2) \end{aligned}$$

$$\cos\theta_1 = \frac{l/2}{\sqrt{r^2 + (l/2)^2}}$$

$$\cos\theta_2 = -\cos\theta_1 = \frac{-l/2}{\sqrt{r^2 + (l/2)^2}}$$

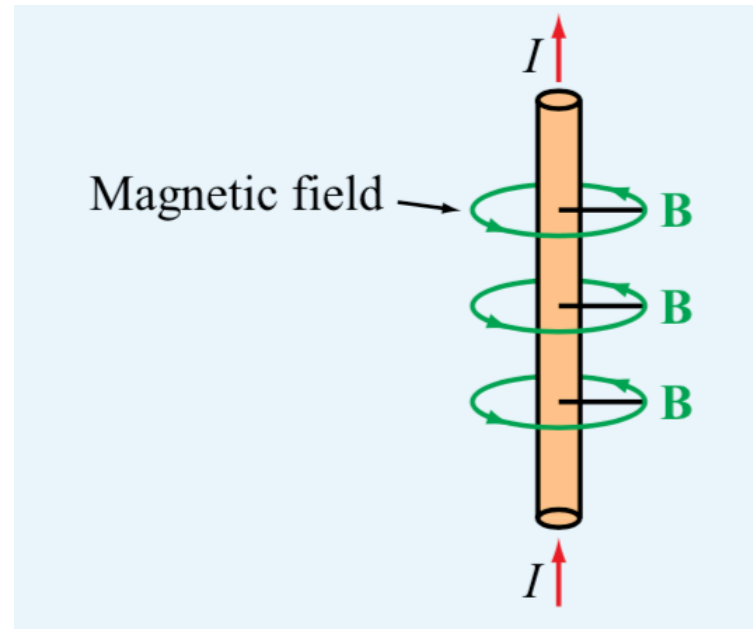
# Magnetic field of linear conductor

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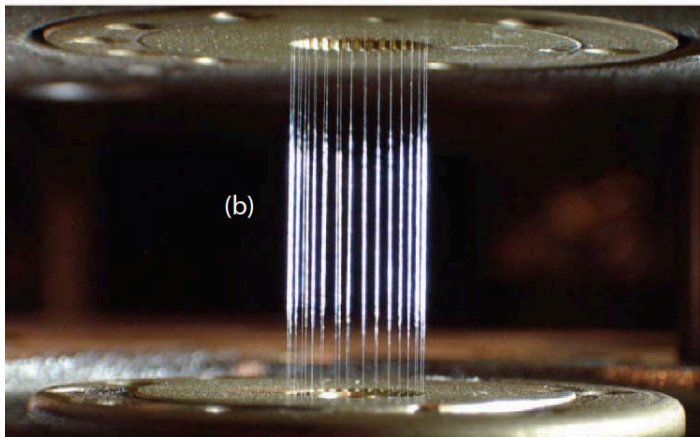
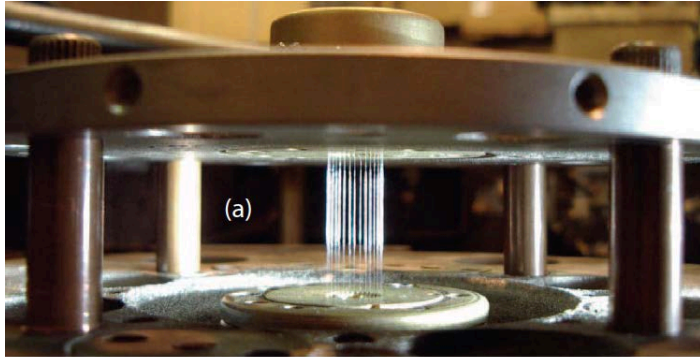
$$\vec{B} = \mu_0 \vec{H} = \hat{\phi} \frac{\mu_0 I l}{2\pi r \sqrt{4r^2 + l^2}}$$

For infinite long wire,  $l \gg r \rightarrow \vec{B} = \hat{\phi} \frac{\mu_0 I}{2\pi r}$

$\vec{B}$  forms concentric circles around wire, with magnitude  $\sim \frac{1}{r}$



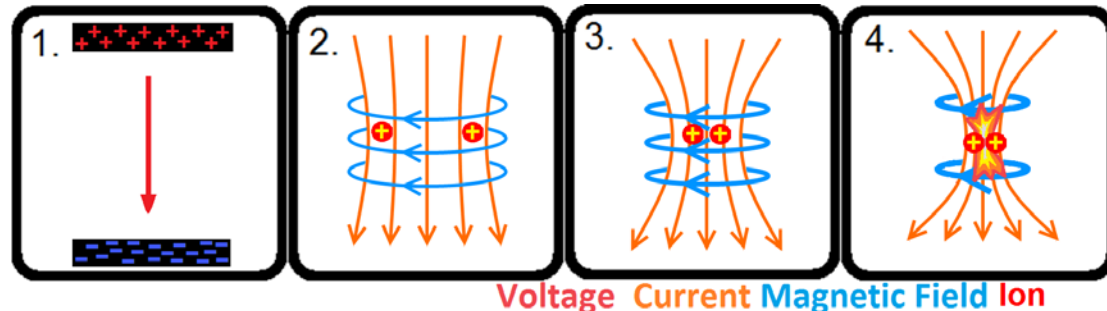
# Example: Lorentz Force for High Energy Density Plasma Research



- 1 Mega Amp pulse over ~300 ns
- Wire array instantly ablates into plasma
- Superposition of magnetic field lines
  - Strong magnetic field on the outside
  - Magnetic “vacuum” on the inside

$$\vec{F} = q\vec{u} \times \vec{B}$$

- Violent plasma cylinder implosion!
  - Variations used for studying wide range of topics, from astrophysics to nuclear fusion



For more details visit:

<https://www.lps.cornell.edu/project/cobra/>

[https://en.wikipedia.org/wiki/Pinch\\_\(plasma\\_physics\)](https://en.wikipedia.org/wiki/Pinch_(plasma_physics))

# Magnetic field of circular loop: Biot-Savart Law

Consider circular loop, radius =  $a$   
carrying  $I \rightarrow$  Find  $\vec{H}$  at a point on axis.

Loop on x-y plane

$$d\vec{H} = \frac{I}{4\pi} \frac{d\vec{l} \times \hat{R}}{R^2}$$

\*  $d\vec{l}$  is  $\perp$  to  $\vec{R}$

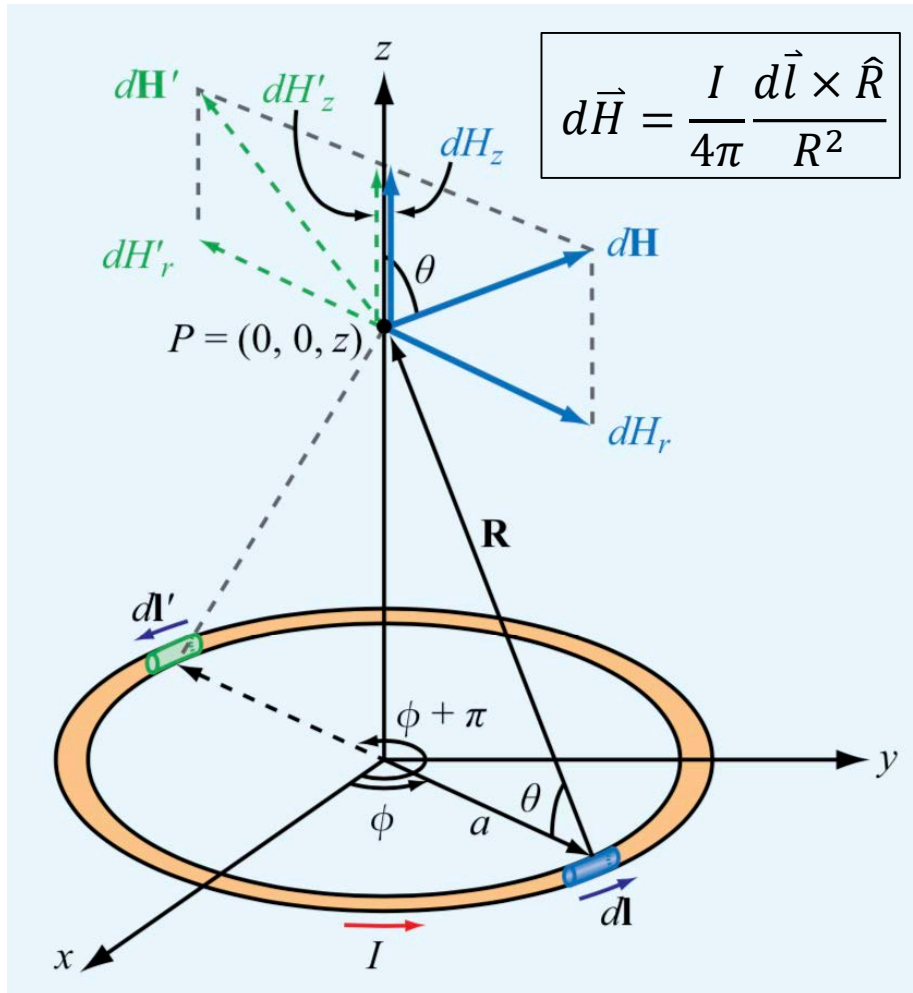
\* All elements around loop are same  
distance to  $P$ :  $R = \sqrt{a^2 + z^2}$

$$dH = \frac{I}{4\pi R^2} |d\vec{l} \times \hat{R}| = \frac{Idl}{4\pi(a^2 + z^2)}$$

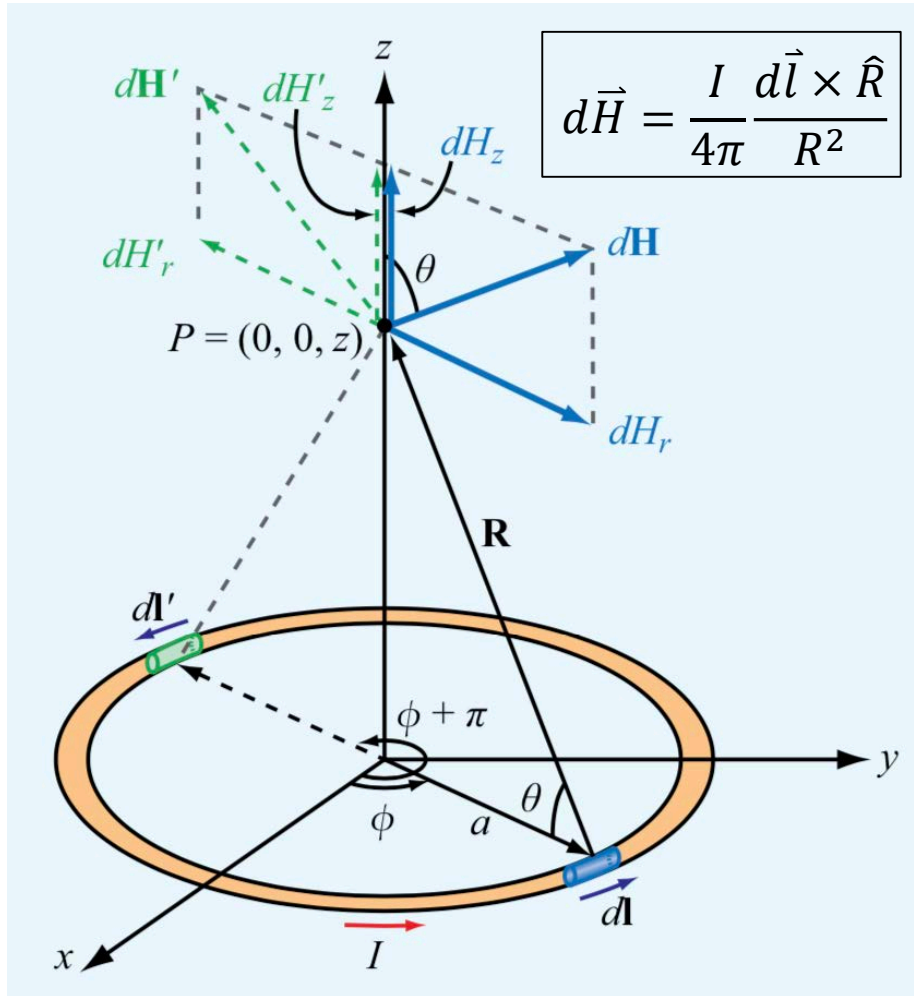
$d\vec{H}$  is  $\perp$  to plane containing  $\vec{R}$  and  $d\vec{l}$

$d\vec{H}$  : in the r-z plane  
 $\rightarrow$  will have  $dH_r$  and  $dH_z$

Note: the z-component of  $d\vec{H}$  will  
add from  $d\vec{l}$ ,  $d\vec{l}'$   
but r-components cancel



# Magnetic field of circular loop: Biot-Savart Law



$$\underbrace{dH'_r = -dH_r}_{\text{cancel}}$$

$$\underbrace{dH'_z = dH_z}_{\text{add}}$$

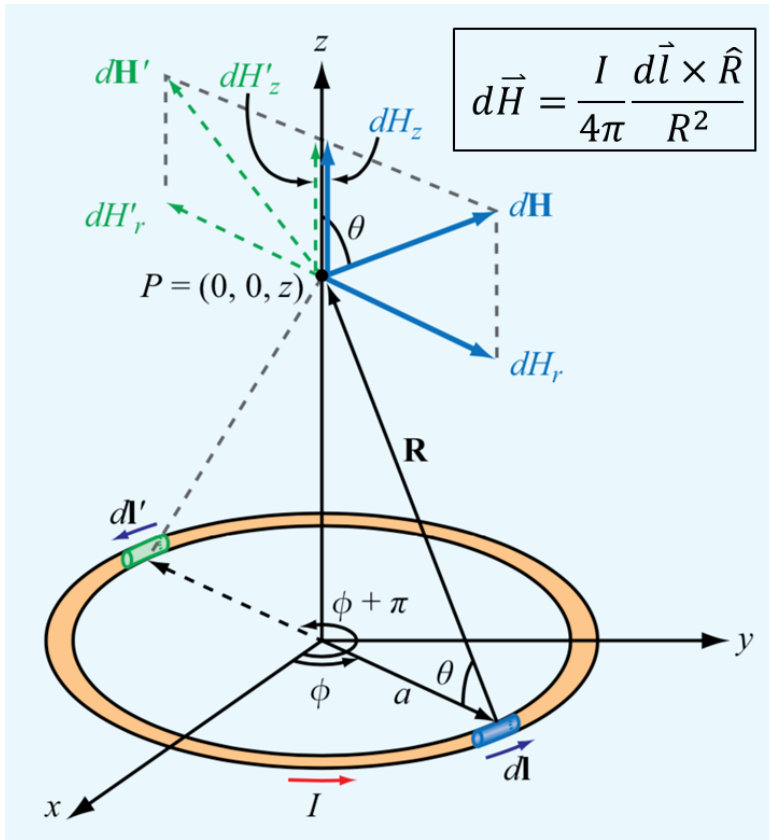
Only  $dH_z$  components remain:

$$d\vec{H} = \hat{z} dH_z = \hat{z} \overbrace{(dH \cos \theta)}^{dH_z}$$

$$= \hat{z} \frac{I \cos \theta}{4\pi(a^2 + z^2)} dl$$

$$d\vec{H} = \hat{z} \frac{I \cos \theta}{4\pi(a^2 + z^2)} dl$$

# Magnetic field of circular loop: Biot-Savart Law



At point P(0,0,z) all quantities are constant, except for  $dl \rightarrow$  so we integrate over  $dl$ :

$$\vec{H} = \hat{z} \frac{I \cos \theta}{4\pi(a^2 + z^2)} \oint_{\text{over circle}} dl$$

$$\vec{H} = \hat{z} \frac{I \cos \theta}{4\pi(a^2 + z^2)} (2\pi a)$$

$$\text{using } \cos \theta = \frac{a}{\sqrt{a^2 + z^2}}$$

$$\boxed{\vec{H} = \hat{z} \frac{I a^2}{2(a^2 + z^2)^{3/2}} \text{ [A/m]}}$$

At  $z = 0$  (center of loop):

$$\vec{H} = \hat{z} \frac{I}{2a}$$

For  $z^2 \gg a^2$  (far from loop):

$$\vec{H} = \hat{z} \frac{I a^2}{2|z|^3}$$

# Electrostatics and Magnetostatics

Attribute	Electrostatics	Magnetostatics
<b>Sources</b>	Stationary charges $\rho_v$	Steady currents $\mathbf{J}$
<b>Fields and Fluxes</b>	$\mathbf{E}$ and $\mathbf{D}$	$\mathbf{H}$ and $\mathbf{B}$
<b>Constitutive parameter(s)</b>	$\epsilon$ and $\sigma$	$\mu$
<b>Governing equations</b> • <b>Differential form</b> • <b>Integral form</b>	$\nabla \cdot \mathbf{D} = \rho_v$ $\nabla \times \mathbf{E} = 0$ $\oint_S \mathbf{D} \cdot d\mathbf{s} = Q$ $\oint_C \mathbf{E} \cdot d\mathbf{l} = 0$	$\nabla \cdot \mathbf{B} = 0$ $\nabla \times \mathbf{H} = \mathbf{J}$ $\oint_S \mathbf{B} \cdot d\mathbf{s} = 0$ $\oint_C \mathbf{H} \cdot d\mathbf{l} = I$
<b>Potential</b>	Scalar $V$ , with $\mathbf{E} = -\nabla V$	Vector $\mathbf{A}$ , with $\mathbf{B} = \nabla \times \mathbf{A}$
<b>Energy density</b>	$w_e = \frac{1}{2} \epsilon E^2$	$w_m = \frac{1}{2} \mu H^2$
<b>Force on charge <math>q</math></b>	$\mathbf{F}_e = q\mathbf{E}$	$\mathbf{F}_m = q\mathbf{u} \times \mathbf{B}$
<b>Circuit element(s)</b>	$C$ and $R$	$L$

# Gauss's Law for Magnetism

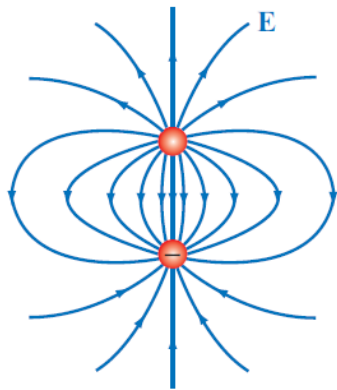
Gauss - Electric  $\vec{\nabla} \cdot \vec{D} = \rho_V \longleftrightarrow \oint_S \vec{D} \cdot d\vec{s} = Q$

Similarly:  $\vec{\nabla} \cdot \vec{B} = 0 \longleftrightarrow \oint_S \vec{B} \cdot d\vec{s} = 0$

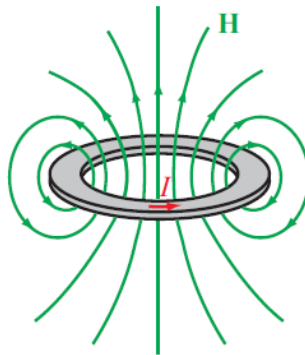
Divergence theorem

No magnetic monopole

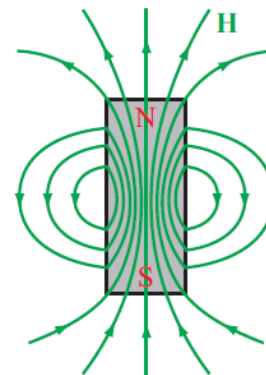
→ magnetic field lines always form continuous closed loops



(a) Electric dipole



(b) Magnetic dipole



(c) Bar magnet

Because a circular loop exhibits a magnetic field pattern similar to the electric field of an electric dipole, it is called a *magnetic dipole*

# Ampère's Law

Electrostatic field conservative:

$$\vec{\nabla} \times \vec{E} = 0 \quad \longleftrightarrow \quad \oint_C \vec{E} \cdot d\vec{l} = 0$$

Stoke's theorem

Surface  $S$ , contour  $C$

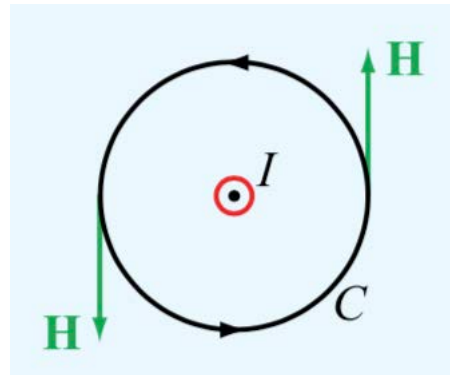
Ampère's Law:

$$\vec{\nabla} \times \vec{H} = \vec{J} \quad \longleftrightarrow \quad \oint_C \vec{H} \cdot d\vec{l} = I$$

Total current through surface,  $S$

$$\int_S (\vec{\nabla} \times \vec{H}) \cdot d\vec{s} = \int_S \vec{J} \cdot d\vec{s} = I$$

Contour follows RHR:  $I$  along thumb, the contour follows RHR



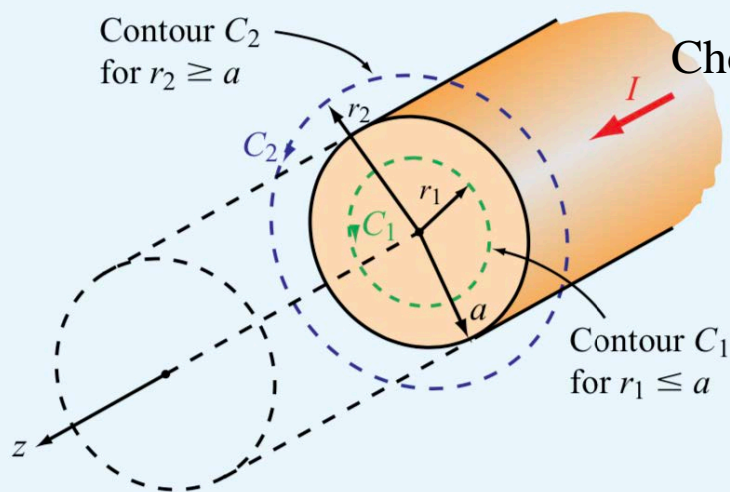
We use symmetry in applying contours, similar to Gaussian surfaces

# Magnetic field of long wires

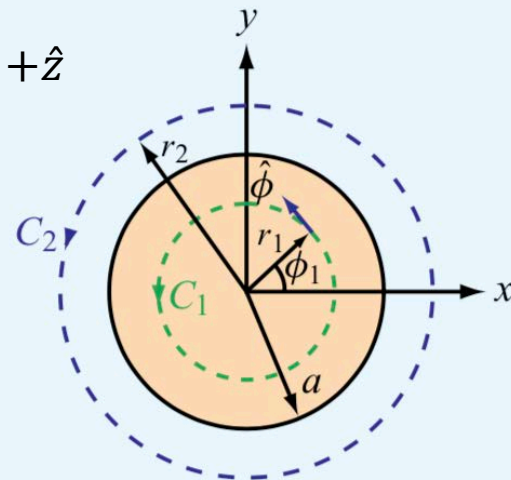
Consider very long straight wire of radius  $a$ , carrying a steady current  $I$  uniformly distributed over cross section.

Find  $\vec{H}$  a distance  $r$  from wire axis for:

- a)  $r \leq a$  (inside wire)
- b)  $r \geq a$  (outside wire)



(a) Cylindrical wire



(b) Wire cross section

# Magnetic field of long wires

1)  $I$  along  $+\hat{z}$ .  $\vec{H}_1 = \vec{H}$  at  $r = r_1 \leq a$

Choose Amperian contour,  $C_1$  as circle of radius,  $r = r_1$

$$\oint_{C_1} \vec{H}_1 \cdot d\vec{l}_1 = I_1 \leftarrow \text{Fraction of total current flowing within } C_1$$

$\vec{H}_1$  by symmetry is constant and parallel to contour

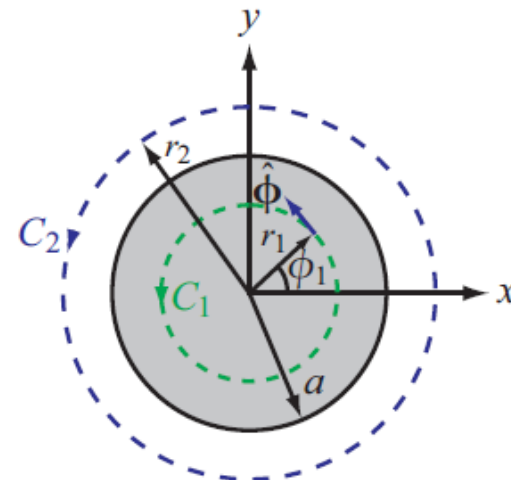
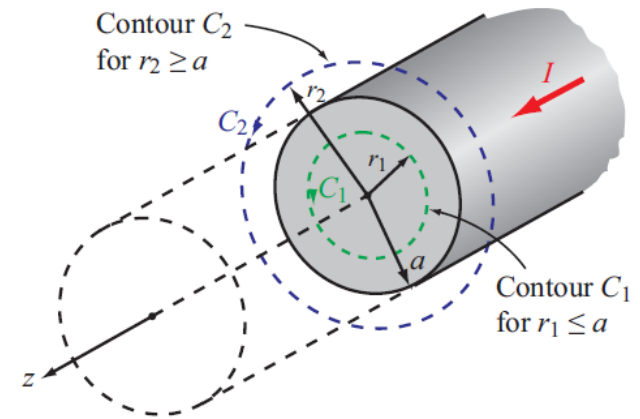
Since  $I$  is along  $+\hat{z}$ ,  $\vec{H}_1$  must be along  $+\hat{\phi}$

$$\vec{H}_1 = \hat{\phi} H_1 \quad d\vec{l}_1 = \hat{\phi} r_1 d\phi$$

$$\oint_{C_1} \vec{H}_1 \cdot d\vec{l}_1 = \int_0^{2\pi} H_1 (\hat{\phi} \cdot \hat{\phi}) r_1 d\phi = 2\pi r_1 H_1$$

$$I_1 = \left( \frac{\pi r_1^2}{\pi a^2} \right) I = \left( \frac{r_1}{a} \right)^2 I$$

$$\vec{H}_1 = \hat{\phi} H_1 = \hat{\phi} \frac{r_1}{2\pi a^2} I \quad r_1 \leq a$$



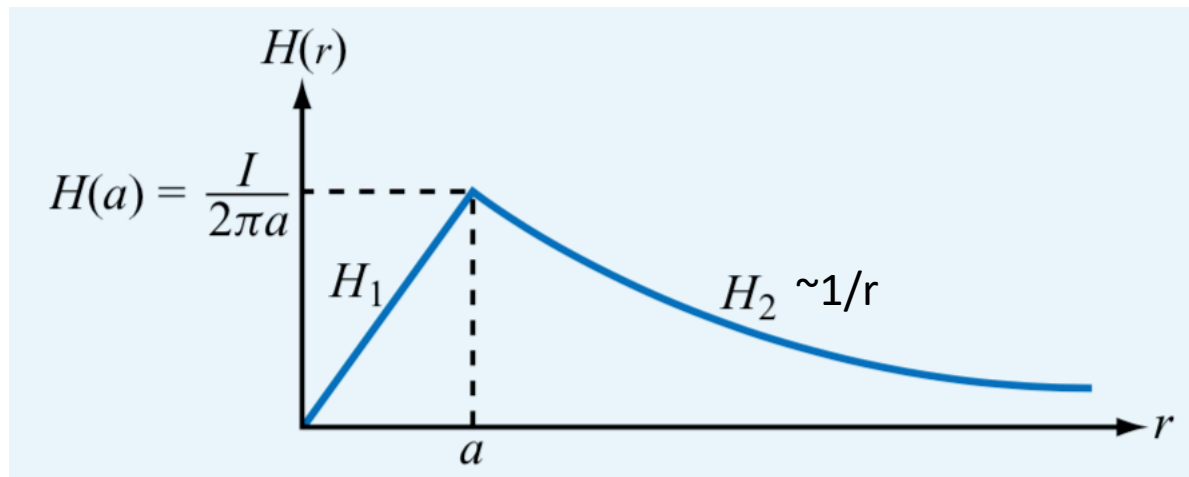
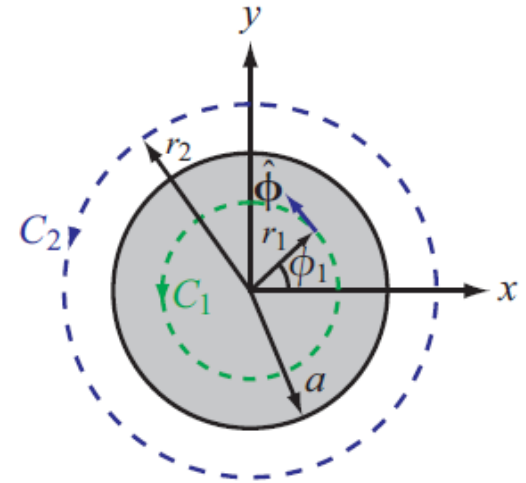
# Example: Magnetic field of long wires

2)  $r = r_2 \geq a$  Choose  $C_2$ , outside wire.

$$\vec{H}_2 = \hat{\phi} H_2 \quad d\vec{l}_2 = \hat{\phi} r_2 d\phi$$

$$\oint_{C_2} \vec{H}_2 \cdot d\vec{l}_2 = 2\pi r_2 H_2 = I$$

$$\vec{H}_2 = \hat{\phi} H_2 = \hat{\phi} \frac{I}{2\pi r_2} \quad r_2 \geq a$$



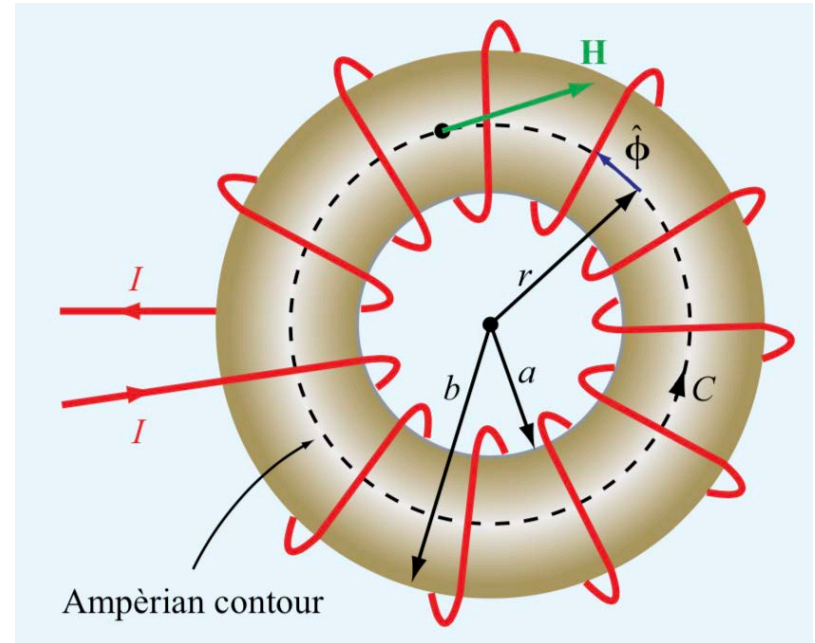
# Magnetic Field of Toroid

Applying Ampere's law over contour C

$$\oint_C \vec{H} \cdot d\vec{l} = I$$

Ampere's law: the line integral of  $\vec{H}$  around a closed contour  $C$  is equal to the current traversing the surface bounded by the contour.

What's the magnetic field outside the toroid?



$$\oint_C \vec{H} \cdot d\vec{l} = \int_0^{2\pi} (-\hat{\phi}H) \cdot \hat{\phi} r d\phi = -2\pi r H = -NI$$

$$\text{Hence, } H = -\frac{NI}{2\pi r} \text{ and } \vec{H} = -\hat{\phi}H = -\hat{\phi} \frac{NI}{2\pi r} \text{ for } a < r < b$$

# Inductance

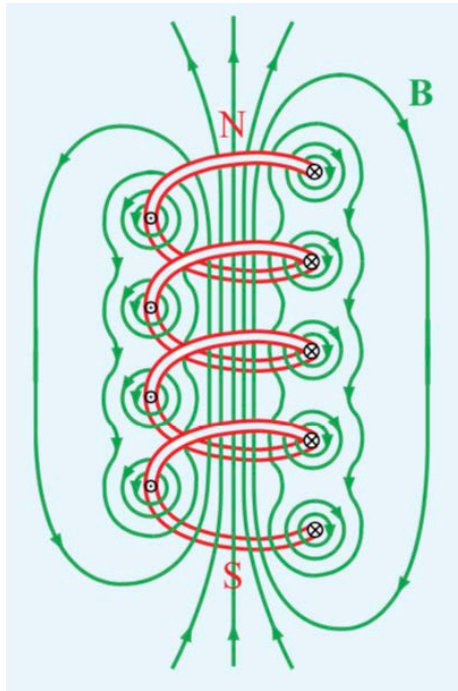
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Inductance → analog of capacitance

Capacitor can store energy in  $\vec{E}$  field between conducting surfaces

Inductor stores energy in  $\vec{H}$  field near current carrying conductors

## Solenoid



Multiple turns of wire – core can be air or magnetic material,  $\mu$

If turns are closely spaced

→ magnetic field can be uniform

→ looks more like permanent magnet

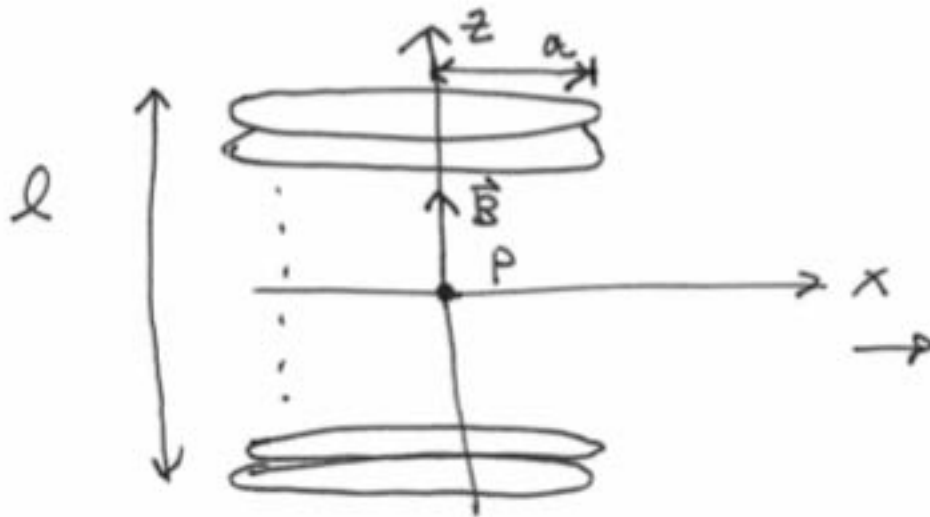
# Magnetic Flux in Solenoid

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Tightly wound solenoid of length =  $l$

Number of turns / unit length:  $n = \frac{N}{l}$

because tight wound, treat helical shape as rings

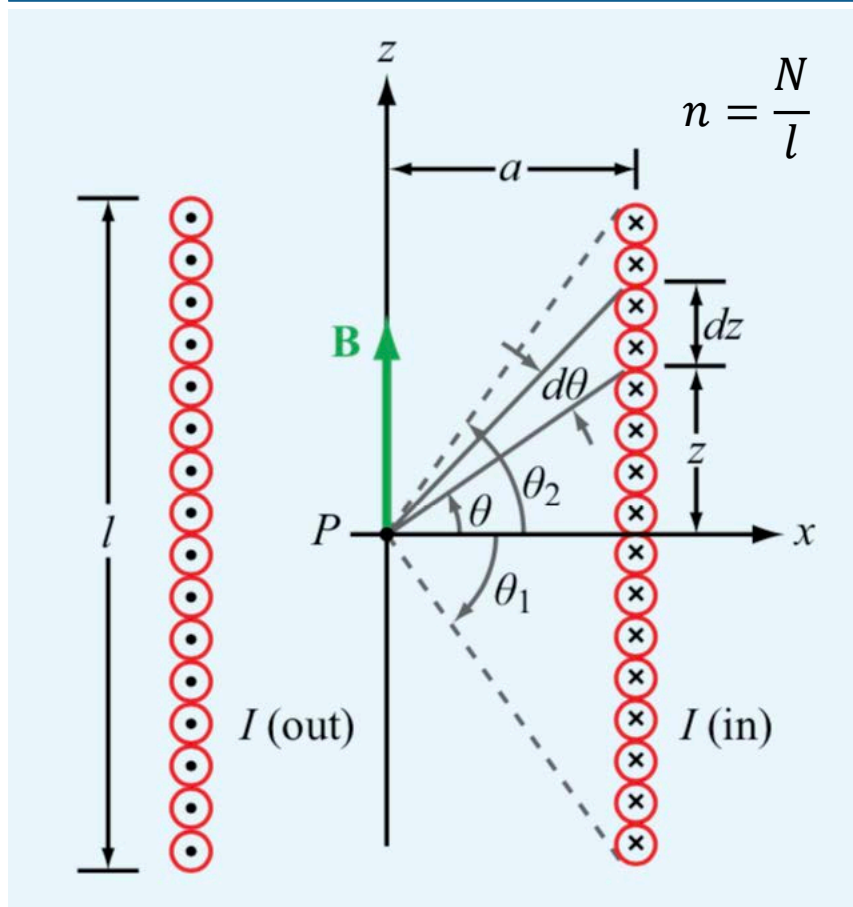


Radius =  $a$

Length =  $l$

Consider  $\vec{B}$  at point  $P$  on axis

# Solenoid



We previously obtained magnetic field,  $\vec{H}$  along axis for 1 loop of current:

$$\vec{H} = \hat{z} \frac{I' a^2}{2(a^2 + z^2)^{3/2}}$$

$a$  = loop radius

$I'$  = current in loop

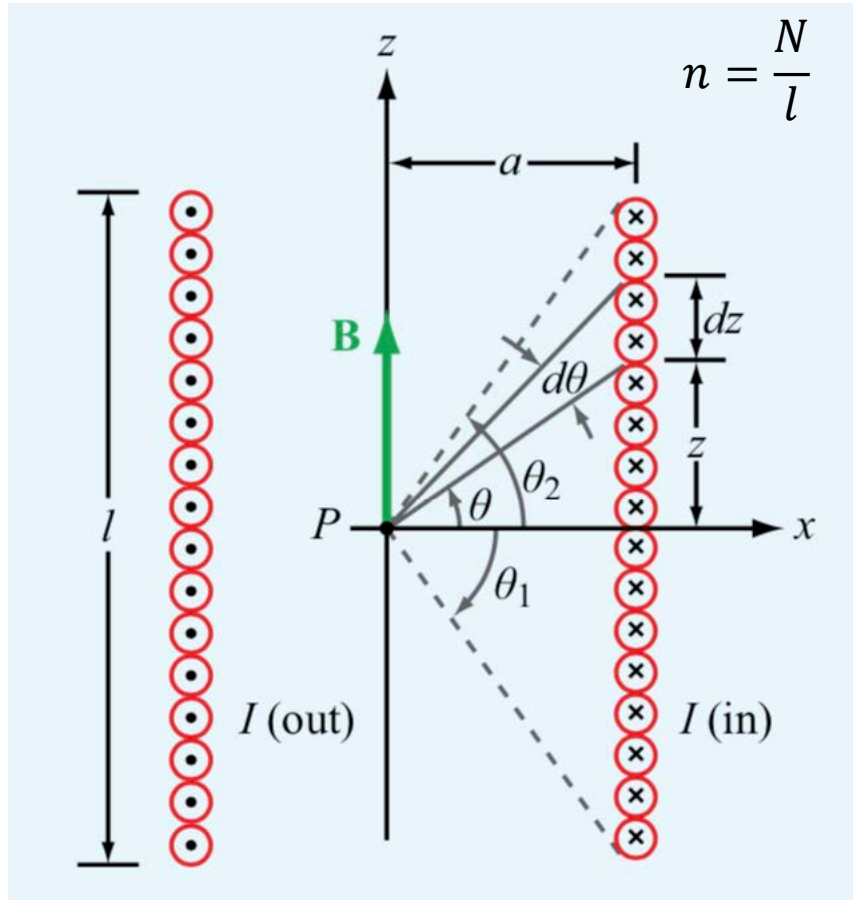
$$n = \frac{N}{l}$$

For solenoid:

$dz$  of solenoid = equivalent to loop composed of  $(ndz)$  turns carrying current

$$I' = I(ndz)$$

# Solenoid



Then, at  $P$ :

$$I' = Indz$$

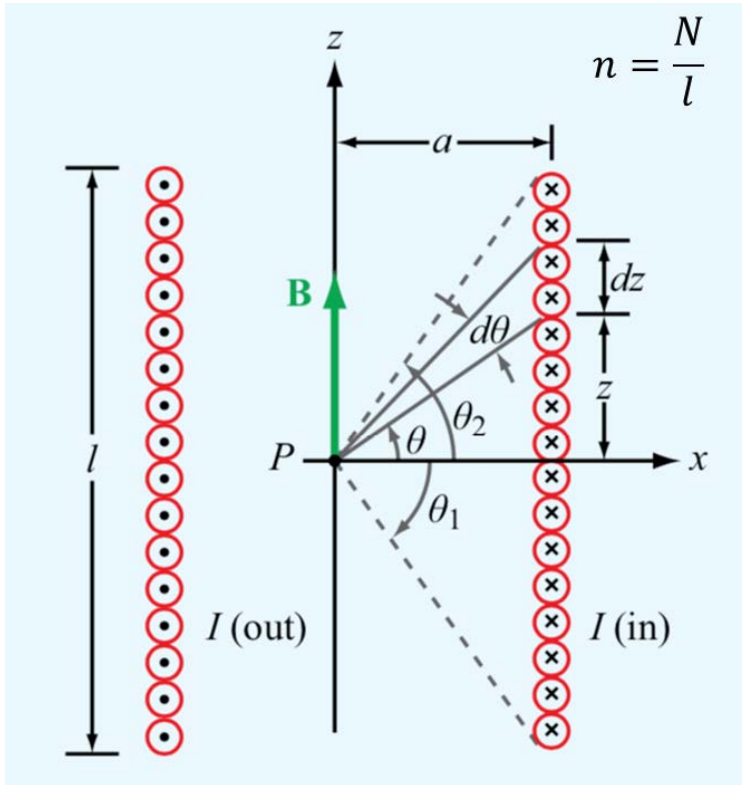
$$d\vec{B} = \mu d\vec{H} = \hat{z} \frac{\mu n I a^2}{2(a^2 + z^2)^{3/2}} dz$$

Total  $\vec{B}$ : integrate over length of solenoid to compute  $\vec{B}$  as seen at  $P$

Angle  $\theta$ : angle as seen from  $P$  of solenoid

$$z = (a)\tan\theta \leftarrow \tan\theta = \frac{z}{a}$$

# Solenoid



$$d\vec{B} = \mu d\vec{H} = \hat{z} \frac{\mu n I a^2}{2(a^2 + z^2)^{3/2}} dz$$

$$z = (a) \tan \theta$$

$$a^2 + z^2 = a^2 + a^2 \tan^2(\theta) = a^2 \sec^2 \theta$$

$$a^2 (1 + \tan^2(\theta))$$

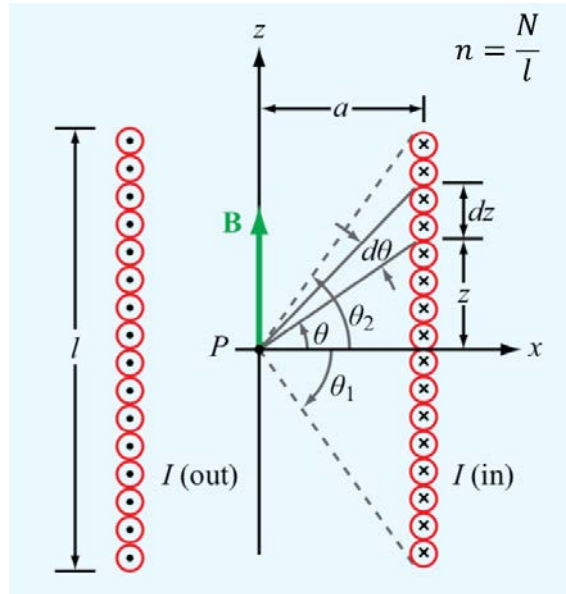
$$dz = a \sec^2 \theta d\theta$$

$$d\vec{B} = \mu d\vec{H} = \hat{z} \frac{\mu n I a^2}{2(a^2 + z^2)^{3/2}} dz$$

$$\vec{B} = \hat{z} \frac{\mu n I a^2}{2} \int_{\theta_1}^{\theta_2} \frac{a \sec^2 \theta d\theta}{a^3 \sec^3 \theta} \left. \begin{array}{l} \vphantom{\int} \right\} = dz \\ \vphantom{\int} \left. \right\} = (a^2 + z^2)^{3/2} \end{array} \right.$$

$$\vec{B} = \hat{z} \frac{\mu n I}{2} (\sin \theta_2 - \sin \theta_1)$$

# Solenoid



$$\vec{B} = \hat{z} \frac{\mu n I}{2} (\sin \theta_2 - \sin \theta_1)$$

If solenoid length  $l \gg a$ , then  $\theta_1 = -\theta_2 \approx \pm 90^\circ$   $\theta_1 \approx -90^\circ$   $\theta_2 \approx 90^\circ$

$$\vec{B} \approx \hat{z} \mu n I = \frac{\hat{z} \mu N I}{l} \quad \text{Long solenoid } l/a \gg 1$$



Holds for  $\vec{B}$  everywhere inside solenoid (except for ends)